Symmetry breaking and restoration in the Ginzburg-Landau model of nematic liquid crystals

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$$E(u) = \int_{\mathbb{R}^2} \frac{1}{2} |\nabla u|^2 - \frac{1}{2\epsilon^2} \mu(x) |u|^2 + \frac{1}{4\epsilon^2} |u|^4 - \frac{a}{\epsilon} f(x) \cdot u, \quad (1)$$

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- μ∈ C[∞](ℝ², ℝ) ∩ L[∞](ℝ², ℝ) is radial i.e. μ(x) = μ_{rad}(|x|), μ'_{rad} < 0 in (0,∞), and μ_{rad}(ρ) = 0 for a unique ρ > 0.
 f = (f₁, f₂) ∈ C[∞](ℝ², ℝ²) ∩ L¹(ℝ², ℝ²) ∩ L[∞](ℝ², ℝ²) is also radial i.e. f(x) = f_{rad}(|x|) x/|x|, and f_{rad} > 0 on (0,∞).



• E admits a global minimizer v solving

$$\epsilon^2 \Delta v + \mu(x)v - |v|^2 v + \epsilon a f(x) = 0, \qquad x \in \mathbb{R}^2.$$
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- the parameter a represents the intensity of the light,

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- the parameter a represents the intensity of the light,
- the vector field v is related to the orientation of the molecules in the liquid crystal.
- The model seems to be good since it confirms the experiments.



Qualitative properties of the global minimizers v as e > 0 is small and a(e) ≥ 0 is bounded uniformly in e. More precisely: existence and location of zeros; profile of v in the regions where µ > 0, |µ| ≪ 1, and µ < 0.</p>

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- Qualitative properties of the global minimizers v as e > 0 is small and a(e) ≥ 0 is bounded uniformly in e. More precisely: existence and location of zeros; profile of v in the regions where µ > 0, |µ| ≪ 1, and µ < 0.</p>
- Symmetry breaking and restoration phenomena as a and e vary. The energy (1) and equation (2) are invariant under the transformations v(x) → g⁻¹v(gx), ∀g ∈ O(2). In addition, ∀e > 0, ∀a > 0 there exists a unique radial solution u(x) = u_{rad}(|x|) x/|x|, (i.e. a solution invariant under the previous transformations).

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- However, the symmetry is broken as soon as a > 0; it is restored for sufficiently large values of a.
- The case a = 0 is special since the global minimizer inherits the radial and one dimensional profile of µ: v(x) = (v_{rad}(|x|), 0) up to change of v by gv with g ∈ SO(2).



We rescale the global minimizers and compute uniform bounds on compact sets up to the second derivatives.

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- Next, by the theorem of Ascoli we obtain the convergence of the rescaled minimizers to a minimal solution η of a new equation:

$$\Delta \eta = \nabla W(\eta), \ \eta : \mathbb{R}^2 \to \mathbb{R}^2, \ W : \mathbb{R}^2 \to \mathbb{R},$$
(3)

that is, $E_W(\eta, \operatorname{supp} \phi) \leq E_W(\eta + \phi, \operatorname{supp} \phi)$, for all $\phi \in C_0^{\infty}(\mathbb{R}^2, \mathbb{R}^2)$, where

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To determine the limit η we need to know the classification of all minimal solutions of (3) and some properties of ν.

In particular, in the case of the Ginzburg-Landau equation

$$\Delta\eta = (|\eta|^2 - 1)\eta, \ \eta : \mathbb{R}^2 \to \mathbb{R}^2, \ W(u) = \frac{1}{4}(|u|^2 - 1)^2, \ (4)$$

we utilize a result of Mironescu (1996): any minimal solution of (4) is either a constant of modulus 1 or (up to orthogonal transformation in the range and translation in the domain) the radial solution $\eta(x) = \eta_{rad}(|x|)\frac{x}{|x|}$.

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- In many situations the limiting equation is trivial, for instance when W is convex.
- Finally, if the classification of minimal solutions to (3) is not available, our method only establishes the existence of a minimal solution to (3) (but we cannot determine it).

Theorem

Let $v_{\epsilon,a}$ be the global minimizer of E, let $a \ge 0$ be bounded (possibly dependent on ϵ), let $\rho > 0$ be the zero of μ_{rad} and let $\mu_1 := \mu'_{rad}(\rho) < 0$. The following statements hold:

(i) Let $\Omega \subset D(0; \rho)$ be an open set such that $v_{\epsilon,a} \neq 0$ on Ω , for every $\epsilon \ll 1$. Then $|v_{\epsilon,a}| \to \sqrt{\mu}$ in $C^0_{\text{loc}}(\Omega)$.

(ii) For every $\xi = \rho e^{i\theta}$, we consider the local coordinates $s = (s_1, s_2)$ in the basis $(e^{i\theta}, ie^{i\theta})$, and the rescaled minimizers:

$$w_{\epsilon,a}(s) = 2^{-1/2} (-\mu_1 \epsilon)^{-1/3} v_{\epsilon,a} \Big(\xi + \epsilon^{2/3} \frac{s}{(-\mu_1)^{1/3}} \Big).$$

As $\epsilon \to 0$, the function $w_{\epsilon,a}$ converges in $C^2_{loc}(\mathbb{R}^2, \mathbb{R}^2)$ up to subsequence, to a bounded in the half-planes $[s_0, \infty) \times \mathbb{R}$ solution of

$$\Delta y(s) - s_1 y(s) - 2|y(s)|^2 y(s) - \alpha = 0, \qquad \forall s = (s_1, s_2) \in \mathbb{R}^2,$$
(5)
with $\alpha = \lim_{\epsilon \to 0} \frac{a(\epsilon)f(\xi)}{\sqrt{2\mu_1}}.$

(iii) For every $r_0 > \rho$, we have $\lim_{\epsilon \to 0} \frac{v_{\epsilon,a}((r_0+t\epsilon)e^{i\theta})}{\epsilon} = -\frac{a_0}{\mu_{rad}(r_0)}f(r_0e^{i\theta}) \text{ uniformly when } t$ remains bounded and $\theta \in \mathbb{R}$, with $a_0 := \lim_{\epsilon \to 0} a(\epsilon)$.

Theorem

Assume that $a(\epsilon) > 0$, a is bounded and $\lim_{\epsilon \to 0} \epsilon^{1-\frac{3\gamma}{2}} \ln a = 0$ for some $\gamma \in [0, 2/3)$.

(i) For $\epsilon \ll$ 1, the global minimizer $v_{\epsilon, a}$ has at least one zero \bar{x}_{ϵ} such that

$$|\bar{x}_{\epsilon}| \leq
ho + o(\epsilon^{\gamma}).$$

In addition, any sequence of zeros of $v_{\epsilon,a}$, either satisfies (6) or it diverges to ∞ .

(ii) For every $\rho_0 \in (0, \rho)$, there exists $b_* > 0$ such that when $\limsup_{\epsilon \to 0} \frac{a}{\epsilon | \ln \epsilon |} < b_*$ then any limit point $l \in \mathbb{R}^2$ of the set of zeros of the global minimizer satisfies

$$\rho_0 \le |I| \le \rho.$$

In addition if $a = o(\epsilon | \ln \epsilon |)$ then $|l| = \rho$, and $\lim_{\epsilon \to 0} |v(x)| = \sqrt{\mu^+(x)}$ uniformly on \mathbb{R}^2 .



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(iii) On the other hand, for every $\rho_0 \in (0, \rho)$, there exists $b^* > 0$ such that when $\limsup_{\epsilon \to 0} \frac{a}{\epsilon |\ln \epsilon|^2} > b^*$, the set of zeros of the global minimizer has a limit point *I* such that

 $|I| \le \rho_0.$

If $v_{\epsilon,a}(\bar{x}_{\epsilon}) = 0$ and $\bar{x}_{\epsilon} \to I$ then up to a subsequence

$$\lim_{\epsilon \to 0} \mathsf{v}_{\epsilon,\mathsf{a}}(\bar{x}_{\epsilon} + \epsilon s) \to \sqrt{\mu(l)}(g \circ \eta)(\sqrt{\mu(l)}s),$$

in $C^2_{\text{loc}}(\mathbb{R}^2)$, for some $g \in O(2)$. In addition if $\limsup_{\epsilon \to 0} \frac{a}{\epsilon |\ln \epsilon|^2} = \infty$ then l = 0.



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Theorem

- (i) Given ε > 0, there exists A > 0 such that for every a > A, the global minimizer v_{ε,a} is unique and radial i.e.
 v(x) = v_{rad}(|x|) x/|x|.
- (ii) When a = 0 the global minimizer can be written as $v(x) = (v_{rad}(|x|), 0)$ with $v_{rad} \in C^{\infty}(\mathbb{R})$ positive. It is unique up to change of v by gv with $g \in SO(2)$.



How we locate the vortices

- ► It is convenient to renormalize the energy: $\begin{aligned} \mathcal{E}(u) &:= E(u) + \int_{|x| < \rho} \frac{\mu^2}{4\epsilon^2} = \\ \int_{\mathbb{R}^2} \frac{1}{2} |\nabla u|^2 + \int_{|x| < \rho} \frac{(|u|^2 - \mu)^2}{4\epsilon^2} + \int_{|x| > \rho} \frac{|u|^2 (|u|^2 - 2\mu)}{4\epsilon^2} - \frac{a}{\epsilon} \int_{\mathbb{R}^2} f \cdot u \end{aligned}$
- We compute an upper bound of *E(v)* by choosing an appropriate test function:

$$\mathcal{E}(\mathsf{v}_{\epsilon,\mathsf{a}}) \leq rac{\pi |\mu_1|
ho}{6} |\ln \epsilon| + \mathcal{O}(1).$$

Then we proceed by contradiction. If v has a zero x̄_ε such that |x̄_ε| ≤ ρ₀ < ρ, it follows that</p>

$$\liminf_{\epsilon \to 0} \mathcal{E}(v_{\epsilon,a}) \geq \left(\lambda(\rho_0) + \frac{\pi |\mu_1|\rho}{6}\right) |\ln \epsilon| - K \frac{a}{\epsilon} + \mathcal{O}(1).$$

• We reach a contradiction if $\limsup_{\epsilon \to 0} \frac{a(\epsilon)}{\epsilon |\ln \epsilon|} < \frac{\lambda(\rho_0)}{K}$.

How we locate the vortices

- On the other hand, if v does not vanish in $D(0; \rho_0)$ with $\rho_0 < \rho$, we have $\mathcal{L}^2\left(\left\{x \in D(0; \rho_0) : \frac{x}{|x|} \cdot \frac{v}{|v|} \leq \frac{1}{2}\right\}\right) \leq \frac{K_2 \epsilon |\ln \epsilon|}{a}.$
- Since the degree of v on the circles |x| = r ∈ (0, ρ₀) is 0 we obtain an increase of energy

$$\int_{D(0;\rho_0)} \left| \nabla \frac{\boldsymbol{v}}{|\boldsymbol{v}|} \right|^2 \geq \frac{(\pi\rho_0)^2 \boldsymbol{a}}{6^2 K_2 \epsilon |\ln \epsilon|} - \frac{4\pi}{3},$$

which contradicts the upper bound $\int_{D(0;\rho_0)} \left| \nabla \frac{\mathbf{v}}{|\mathbf{v}|} \right|^2 \leq K_1 |\ln \epsilon|$ when $\limsup_{\epsilon \to 0} \frac{\mathbf{a}(\epsilon)}{\epsilon^2 |\ln \epsilon|} < \frac{6^2 K_1 K_2}{(\pi \rho_0)^2}$. The vector Painlevé equation $y : \mathbb{R}^2 \to \mathbb{R}^2$

$$\Delta y(s) - s_1 y(s) - 2|y(s)|^2 y(s) - \alpha = 0, \qquad \forall s = (s_1, s_2) \in \mathbb{R}^2, \ (6)$$

with $\alpha = \lim_{\epsilon \to 0} \frac{a(\epsilon)f(\xi)}{\sqrt{2}\mu_1} \in \mathbb{R}^2$,

▶ generalizes the second Painlevé O.D.E. $y : \mathbb{R} \to \mathbb{R}$

$$y'' - sy - 2y^3 - \alpha = 0, \qquad s \in \mathbb{R}.$$
 (7)

In a previous paper we showed that this last equation plays an analogous role in the one dimensional, scalar version of the problem.



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Open question

- Numerical simulations suggest that in 1D and 2D, the rescaled profile of the shadow vortex comes from the generalized second Painlevé equation, and not from the Ginzburg-Landau equation (like the standard vortex).

Related problems

- The energy E belongs to the class of Ginzburg-Landau type functionals that appear for example in the theory of superconductivity or in the theory of Bose-Einstein condensates.
- For these problems there also exist threshold values of the parameters that determine the structure of the global minimizers. According to these values, the global minimizer may or may not have vortices.

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